

Single-peakedness and coalition-proofness

Bezalel Peleg¹, Peter Sudhölter²

 ¹ Institute of Mathematics and Center for Rationality and Interactive Decision Theory, The Hebrew University, Givat Ram, 91904 Jerusalem, Israel (e-mail: pelegba@math.huji.ac.il)
² Institute of Mathematical Economics, University of Bielefeld, Postfach 100131, D-33501 Bielefeld, Germany (e-mail: psudhoelter@wiwi.uni-bielefeld.de)

Received: 16 July 1998 / Accepted 23 March 1999

Abstract. We prove that multidimensional generalized median voter schemes are coalition-proof.

JEL classification: C72, D71

Key words: Single-peaked preference, coalition-proof equilibrium, generalized median voter scheme

1 Introduction

It is well-known that the majority rule is not transitive. In order to guarantee transitivity we have to restrict the preferences of the voters. The first well-known restriction is single-peakedness, which was introduced by Arrow (1951) and Black (1948). The median voter scheme over the domain of single-peaked preferences was shown to be compatible with Condorcet's rule. Moulin (1980) has introduced generalized median voter schemes over one-dimensional sets of alternatives. His paper includes, among other results, both the characterization of all strategy-proof voting schemes, and the characterization of anonymous, strategyproof, and Paretian generalized median voter schemes. He also characterized the family of schemes which only satisfy anonymity and strategy-proofness. Border and Jordan (1983) extended generalized median voter schemes to multidimensional sets of alternatives. As far as we know, the latest generalization of Moulin (1980) is due to Barberá, Gul and Stacchetti (1993). They consider generalized median voter schemes over multi-dimensional sets of alternatives. As expected, they restrict their analysis to multi-dimensional single-peaked preferences. One of their important results is that multi-dimensional generalized median

We are grateful to two anonymous referees for some helpful remarks. The second author was partially supported by the Edmund Landau Center for Research in Mathematical Analysis and Related Areas, sponsored by the Minerva Foundation (Germany)

voter schemes are characterized by strategy-proofness. We prove in this work that multi-dimensional generalized median voter schemes are also coalition-proof. For the notion of coalition-proofness see Bernheim, Peleg, and Whinston (1987). Coalition-proofness may be regarded as an interesting stability property to be satisfied by voting schemes, because in many cases the voters may have the opportunity to communicate prior to vote. Therefore, generalized median voter schemes being coalition-proof means that they generate "agreements" which are immune to self-enforcing improving deviations. Peleg (1998) shows that pivotal mechanisms are not coalition-proof. We now shall explain and motivate our result.

Let N be a set of n = 2k + 1, k > 1, voters, let B be a (finite) set of alternatives, and let P_0 be a fixed linear ordering of B. Assume that the preferences of the members of N on B are restricted to be single-peaked with respect to P_0 . Then, the median voter scheme is strategy-proof and Paretian. Moreover, the median voter's peak is an outcome of a strong Nash equilibrium (with respect to the true preferences). Thus, under the foregoing assumptions, the median voter scheme is group strategy-proof. This result remains true, if we replace the median voter scheme by a generalized median voter scheme (see Moulin 1980). However, Barberá, Sonnenschein, and Zhou (1991) show that multi-dimensional generalized median voter schemes are not coalitionally strategy-proof. In this paper we address the following problem: What is the strongest kind of group stability which is satisfied by all generalized median voter schemes? We solve the foregoing problem in Sects. 4 and 5: Theorem 4.1 proves that every multidimensional generalized median voter scheme is coalition-proof. Furthermore, in Sect. 5 we give an example of a generalized median voter scheme which is not strongly coalition-proof.

We now briefly review the contents of this paper. Section 2 contains preliminary definitions and Sect. 3 introduces generalized median voter schemes. The proof of the coalition-proofness of multi-dimensional generalized median voter schemes is presented in Sect. 4. An example of a generalized median voter scheme which is not strongly coalition-proof, is given in Sect. 5. Finally, some remarks are contained in Sect. 6.

2 Definitions and notations

A game in strategic form is a system $G = (N, (A_i)_{i \in N}, (u_i)_{i \in N})$ where *N* is a finite set of players; A_i , $i \in N$, is the (non-empty) set of strategies of *i*; and $u_i : \times_{j \in N} A_j \to R$ is the payoff function of player $i \in N$. (Here *R* is the set of real numbers.) Let $S \subset N$, $S \neq \emptyset$. We denote $A_S = \times_{i \in S} A_i$ and $A = A_N$. If $x \in A$ then x_S denotes the restriction of *x* to *S*.

Let $G = (N, (A_i)_{i \in N}, (u_i)_{i \in N})$ be a strategic game, let $S \subset N$, $S \neq \emptyset$, and let $x \in A$. The **reduced game** of G with respect to (w.r.t.) S and x is the game $G^{S,x} = (S, (A_i)_{i \in S}, (u_i^x)_{i \in S})$, where $u_i^x(y_S) = u_i(y_S, x_{N \setminus S})$ for all $y_S \in A_S$ and $i \in S$.

Single-peakedness and coalition-proofness

Let $G = (N, (A_i)_{i \in N}, (u_i)_{i \in N})$ be a strategic game. $x \in A$ is a Nash equilibrium (NE) of G if, for every $i \in N$, $u_i(x) \ge u_i(y_i, x_{N \setminus \{i\}})$ for all $y_i \in A_i$. We now define coalition-proofness by induction on the number of players.

- **Definition 2.1.** (1) In a single player game G, $x \in A$ is a coalition-proof Nash equilibrium (CPNE) if and only if it is an NE.
- (2) Let n > 1 and assume that CPNE has been defined for games with fewer than n players. Then
 - a) For any game G with n players, $x \in A$ is self-enforcing if, for all $S \subset N$, $S \neq \emptyset, N, x_S$ is a CPNE in the reduced game $G^{S,x}$.
 - b) For any game G with n players, $x \in A$ is a CPNE if it is self-enforcing and if there does not exist another self-enforcing strategy vector $y \in A$ such that $u_i(y) > u_i(x)$ for all $i \in N$.

Clearly, a CPNE of a game G is an NE of G. The following definition is closely related to Kaplan's definition of semi-strong equilibrium (see Kaplan 1992).

Definition 2.2. Let $G = (N, (A_i)_{i \in N}, (u_i)_{i \in N})$ be a strategic game and let $x \in A$. x is a strong CPNE if

- (1) x is an NE of G;
- (2) for every $S \subset N$, $S \neq \emptyset$, and every NE y_S of $G^{S,x}$, there exists $i \in S$ such that $u_i(x) \ge u_i(y_S, x_{N\setminus S})$.

Clearly, a strong CPNE of G is a CPNE of G.

NE's, CPNE's and SCPNE's are ordinal concepts, that is, they are generalized in a straightforward manner to ordinal games $(N, (A_i)_{i \in N}, (p_i)_{i \in N})$, where Nand A_i are defined as above and p_i is a preference (i.e. a complete and transitive binary relation) on A. If C is a set and $f : A \to C$ is an "outcome function", then every profile $(P_i)_{i \in N}$ of preferences on C induces a profile $(p_i)_{i \in N}$ of preferences on A by $ap_i b$ iff $f(a)P_i f(b)$ for all $a, b \in A$ and $i \in N$. We write $(N, (A_i)_{i \in N}, f, (P_i)_{i \in N})$ for $(N, (A_i)_{i \in N}, (p_i)_{i \in N})$.

3 Generalized median voter schemes

In this section we recall some definitions of Barberá et al. (1993) which are essential for our work.

Definition 3.1. For integers $a \leq b$, [a,b] will denote the set $\{a, a + 1, ..., b\}$. An ℓ -dimensional **box** B is a cartesian product of ℓ integer intervals: $B = \times_{j=1}^{\ell} B^j$ where $B^j = [a^j, b^j]$ and $a^j \leq b^j$.

Let *B* be an ℓ -dimensional box. We consider *B* as a metric subspace of the space R^{ℓ} with the L_1 -norm. (The L_1 -norm of $\alpha \in R^{\ell}$ is $||\alpha|| = \sum_{j=1}^{\ell} |\alpha^j|$.) A linear order on *B* is a complete (and, thus, reflexive), transitive, and antisymmetric binary relation on *B*. If *P* is a linear order on *B*, then $\tau(P)$ will denote the (unique) maximum of *P* on *B*.

Definition 3.2. A linear order *P* on *a* box *B* is **multi-dimensional single-peaked** with bliss point $\alpha \in B$ if and only if (i) $\tau(P) = \alpha$, and (ii) $\beta P \gamma$ for all $\beta, \gamma \in B$ satisfying $\|\alpha - \gamma\| = \|\alpha - \beta\| + \|\beta - \gamma\|$.

If B is an ℓ -dimensional box, then we denote by $\pi = \pi(B)$ the set of all single-peaked preferences with bliss point in B. Let B be an ℓ -dimensional box and let $N = \{1, ..., n\}$ be a (finite) set of players.

Definition 3.3. A social choice function is a map $\varphi : \pi^N \to B$. A social choice function φ is a voting scheme if there exists a function $f : B^N \to B$ such that

 $\varphi(P_1,\ldots,P_n) = f(\tau(P_1),\ldots,\tau(P_n))$ for all $(P_1,\ldots,P_n) \in \pi^N$

(f will also be called a voting scheme).

We shall be interested in the following class of voting schemes. First we need an auxiliary definition.

Definition 3.4. Let B = [a,b] be a one-dimensional box and $N = \{1,...,n\}$. A **left-coalition system** on B is a correspondence $W : B \rightarrow 2^N$ satisfying the following conditions:

(1) If $\xi \in B$, $C \in W(\xi)$, and $D \supset C$, then $D \in W(\xi)$; (2) If $\xi, \eta \in B$ and $\xi < \eta$, then $W(\xi) \subset W(\eta)$ and (3) $W(b) = 2^N$.

Left-coalition systems induce voting schemes in a natural way. For each $\tilde{\alpha} = (\alpha_1, \ldots, \alpha_n) \in B^N$ and $\xi \in B$, let $C(\tilde{\alpha}, \xi) = \{i \in N | \alpha_i \leq \xi\}$ be the coalition to the left of ξ .

Definition 3.5. Let B = [a,b] be an integer interval and let $W(\cdot)$ be a leftcoalition system on B. The voting scheme $f : B^N \to B$, defined as follows:

$$f(\tilde{\alpha}) = \min\{\xi | C(\tilde{\alpha}, \xi) \in W(\xi)\} \text{ for all } \tilde{\alpha} \in B^N$$

is called the **generalized median voter scheme** (GMVS) induced by $W(\cdot)$. When $B = \times_{j=1}^{\ell} B^j$ is an ℓ -dimensional box, the voting scheme $f : B^N \to B$ is a GMVS if $f = (f^1, \ldots, f^{\ell})$ and each f^j is the GMVS induced by some left-coalition system $W^j(\cdot)$ on B^j .

4 GMVS's are coalition-proof

Let *B* be an ℓ -dimensional box, let $N = \{1, ..., n\}$, and let $f : B^N \to B$ be a GMVS. For $\tilde{P} = (P_1, ..., P_n) \in \pi^N$ we consider the strategic game

$$G(f; P_1, \ldots, P_n) = (N; B, \ldots, B; f; P_1, \ldots, P_n).$$

Here *B* is the set of strategies of player $i \in N$; *f* is the outcome function; and P_1, \ldots, P_n are the preferences of the players on the outcome space. *f* is **coalition-proof** if for every $\tilde{P} = (P_1, \ldots, P_n) \in \pi^N$, the *n*-tuple $\tilde{\alpha} = \tilde{\alpha}(\tilde{P}) = (\tau(P_1), \ldots, \tau(P_n))$ is a CPNE of $G(f; P_1, \ldots, P_n)$.

Theorem 4.1. Every GMVS is coalition-proof.

Proof. We shall prove our claim by induction on the number of players n.

Step 1. n = 1.

Let $B = \times_{j=1}^{\ell} B^j$ be an ℓ -dimensional box and let $f : B \to B$ be a GMVS. If $P \in \pi(B)$ then $\tau(P)$ is a dominant strategy in G(f; P) = (N; B; f; P), because f is strategy-proof. Hence $\tau(P)$ is an NE of G(f; P).

Assume now that every GMVS with k players, $1 \le k < n$, is coalition-proof. Let $N = \{1, ..., n\}$, let $B = \times_{j=1}^{\ell} B^j$ be an ℓ -dimensional box, let $W^j : B^j \to 2^N$ be a left-coalition system on B^j , $j = 1, ..., \ell$, and let $f : B^N \to B$ be the GMVS which is induced by $W^j(\cdot)$, $j = 1, ..., \ell$. Furthermore, let $P_1, ..., P_n \in \pi(B)$, and $\alpha_i = \tau(P_i)$, i = 1, ..., n. We shall prove that $\tilde{\alpha} = (\alpha_1, ..., \alpha_n)$ is a CPNE of $G(f; P_1, ..., P_n)$.

Step 2. $\tilde{\alpha}$ is self-enforcing.

For each $S \subset N$, $S \neq \emptyset, N$, and each $j = 1, ..., \ell$, define the (reduced) leftcoalition system $W^{j}_{S,\tilde{\alpha}}$ on B^{j} by

$$T \in W^{j}_{S,\tilde{\alpha}}(\xi) \Leftrightarrow T \cup \{i \in N \setminus S \mid \alpha^{j}_{i} \leq \xi\} \in W^{j}(\xi)$$

for all $T \subset S$ and all $\xi \in B^j$. As the reader may easily verify $W_{S,\tilde{\alpha}}^j$ is a left-coalition system on B^j (w.r.t. the set of players S). Denote by $f^{S,\tilde{\alpha}}$ the GMVS which is induced by $W_{S,\tilde{\alpha}}^j$, $j = 1, \ldots, \ell$. Then $G(f^{S,\tilde{\alpha}}; (P_i)_{i \in S}) =$ $(S; B^S; f^{S,\tilde{\alpha}}; (P_i)_{i \in S})$ is the reduced game of $G(f; P_1, \ldots, P_n)$ w.r.t. S and $\tilde{\alpha}$. By the induction hypothesis $\tilde{\alpha}_S = (\alpha_i)_{i \in S}$ is a CPNE of $G(f^{S,\tilde{\alpha}}; (P_i)_{i \in S})$. Because this is true for each proper subset of N, $\tilde{\alpha}$ is self-enforcing.

Step 3. $\tilde{\alpha}$ is a CPNE.

Assume, on the contrary, that $\tilde{\alpha}$ is not a CPNE. Then, there exists $\tilde{\beta} \in B^N$ such that (i) $\tilde{\beta}$ is self-enforcing (in the game $G(f; P_1, \ldots, P_n)$), and $f(\tilde{\beta}) \neq f(\tilde{\alpha})$; and (ii) $f(\tilde{\beta})P_if(\tilde{\alpha})$ for $i = 1, \ldots, n$. We denote $s = f(\tilde{\alpha})$ and $t = f(\tilde{\beta})$. Let $s = (\xi^1, \ldots, \xi^\ell)$ and $t = (\eta^1, \ldots, \eta^\ell)$. We distinguish the following possibilities.

(4.1) There exists $m \in \{1, \ldots, \ell\}$ such that $\xi^m < \eta^m$. Let $Q = \{i \in N \mid \alpha_i^m \le \xi^m$ and $\beta_i^m > \xi^m\}$. Q is non-empty because $\xi^m < \eta^m$. Without loss of generality $Q = \{1, \ldots, r\}$ and $\alpha_1^m \le \ldots \le \alpha_r^m$. Now replace sequentially, in $\beta^m = (\beta_1^m, \ldots, \beta_n^m), \beta_i^m$ by $\alpha_i^m, i = 1, \ldots, r$. There exists $k, 1 \le k \le r$ such that $f^m(\alpha_1^m, \ldots, \alpha_{k-1}^m, \beta_k^m, \ldots, \beta_n^m) = \eta^m$ and $f^m(\alpha_1^m, \ldots, \alpha_k^m, \beta_{k+1}^m, \ldots, \beta_n^m) = \zeta < \eta^m$. By the choice of $k, \alpha_k^m \le \zeta$. Thus, all the members of $Q^* = \{1, \ldots, k\}$ strictly prefer $\alpha^m \mid Q^*$ to $\beta^m \mid Q^*$ at $\tilde{\beta}$ ($\alpha^m \mid Q^* = (\alpha_i^m \mid i \in Q^*)$ etc.). That is, Q^* can improve upon $\tilde{\beta}$ by playing ($\alpha^m \mid Q^*, \beta^{-m} \mid Q^*$), where $\beta^{-m} = (\beta^j \mid j \in \{1, \ldots, \ell\} \setminus \{m\})$.

(4.2) There exists $m \in \{1, ..., \ell\}$ such that $\eta^m < \xi^m$. Let $Q = \{i \in N \mid \alpha_i^m \ge \xi^m$ and $\beta_i^m < \xi^m\}$. Clearly, $Q \neq \emptyset$. Without loss of generality $Q = \{1, ..., r\}$ and $\alpha_1^m \ge ... \ge \alpha_r^m$. Now replace sequentially, in $\beta^m = (\beta_1^m, ..., \beta_n^m)$, β_i^m by α_i^m ,

 $i = 1, \ldots, r$. For some $k, 1 \le k \le r, f^m(\alpha_1^m, \ldots, \alpha_k^m, \beta_{k+1}^m, \ldots, \beta_n^m) = \zeta > \eta^m$, and $\zeta \le \alpha_k^m$. Thus, all the members of $Q^* = \{1, \ldots, k\}$ strictly prefer $\alpha^m \mid Q^*$ to $\beta^m \mid Q^*$ at $\tilde{\beta}$.

We call a coalition Q regretful if there exists $m \in \{1, \ldots, \ell\}$ such that Q can improve upon $\tilde{\beta}$ by playing $(\alpha^m \mid Q, \beta^{-m} \mid Q)$. $f(\tilde{\alpha}) \neq f(\tilde{\beta})$ implies that (4.1) or (4.2) is true. Hence, we have proved the existence of a non-empty regretful coalition. Let T be a (non-empty) regretful coalition of minimum size. The following claim is true.

Claim 4.2. For each $m = 1, ..., \ell$, $f((\alpha^m | T, \beta^{-m} | T), \tilde{\beta}^{N \setminus T}) P_i f(\tilde{\beta})$ for all $i \in T$. *Proof of Claim 4.2.* Let $1 \le m \le \ell$. We denote

$$T_{-} = \{ i \in T \mid \alpha_{i}^{m} < \eta^{m} \}, \quad T_{0} = \{ i \in T \mid \alpha_{i}^{m} = \eta^{m} \}, \text{ and} \\ T_{+} = \{ i \in T \mid \alpha_{i}^{m} > \eta^{m} \}.$$

We have to consider seven cases.

(4.3) $T_{-} \neq \emptyset$, $T_{0} \neq \emptyset$, and $T_{+} \neq \emptyset$. Without loss of generality $T_{0} = \{1, \ldots, r\}$, $T_{-} = \{r + 1, \ldots, r + k\}$ and $\alpha_{r+1}^{m} \leq \ldots \leq \alpha_{r+k}^{m}$, $T_{+} = \{r + k + 1, \ldots, q\}$, where qis the number of members of T, and $\alpha_{r+k+1}^{m} \geq \ldots \geq \alpha_{q}^{m}$. First, for $i \in T_{0}$ replace β_{i}^{m} in $\beta^{m} = (\beta_{1}^{m}, \ldots, \beta_{n}^{m})$ by α_{i}^{m} . Clearly $f^{m}(\alpha^{m}|T_{0}, \beta^{m}|N \setminus T_{0}) = \eta^{m}$. Now replace sequentially in $(\alpha^{m}|T_{0}, \beta^{m}|N \setminus T_{0}) \beta_{i}^{m}$ by α_{i}^{m} for $i = r + 1, \ldots, r + k$. By the minimality of T and (i), i=1,2, of Definition 3.4 $f^{m}(\alpha^{m}|T_{0} \cup T_{-}, \beta^{m}|N \setminus (T_{0} \cup T_{-})) = \eta^{m}$. (The rôle of (i), i=1,2, of Definition 3.4 is to guarantee that the order of replacement, first T_{0} and then T_{-} , does not matter.) Similarly, we may show, by replacing sequentially $\beta^{m} | T_{+}$ by $\alpha^{m} | T_{+}$, that $f^{m}(\alpha^{m}|T, \beta^{m}|(N \setminus T)) = \eta^{m}$.

A careful examination of the proof of (4.3) reveals that if at least two out of the three sets T_-, T_0 and T_+ are non-empty, then $f^m(\alpha^m | T, \beta^m | N \setminus T) = \eta^m$. Thus it remains to consider the following three cases.

(4.4) $T_0 \neq \emptyset$, $T_- = T_+ = \emptyset$. Clearly, in this case $f^m(\alpha^m | T, \beta^m | N \setminus T) = \eta^m$.

(4.5) $T_{-} \neq \emptyset$, $T_{0} = T_{+} = \emptyset$. Again, an examination of the proof of (4.3) reveals that $\zeta = f^{m}(\alpha^{m}|T, \beta^{m}|N \setminus T)$ satisfies $\zeta \leq \eta^{m}$ and $\zeta \geq \alpha_{i}^{m}$, $i \in T$. Hence, the claim is proved in this case.

(4.6) $T_+ \neq \emptyset$, $T_0 = T_- = \emptyset$. An examination of the proof of (4.3) reveals that $\zeta = f^m(\alpha^m | T, \beta^m | N \setminus T)$ satisfies $\zeta \ge \eta^m$ and $\zeta \le \alpha_i^m$, $i \in T$.

Let *T* be a (non-empty) minimal (in size) regretful coalition. We conclude from Claim 4.2 that $f(\tilde{\alpha}|T, \tilde{\beta}|N \setminus T) \neq f(\tilde{\beta})$ and $f(\tilde{\alpha}|T, \tilde{\beta}|N \setminus T)P_if(\tilde{\beta})$ for all $i \in T$. Therefore $T \neq N$, because, by hypothesis, $f(\tilde{\beta})P_if(\tilde{\alpha})$ for i = 1, ..., n. Now consider the reduced game $(B^T; f^{T,\beta}; (P_i)_{i\in T})$. By the induction hypothesis $\tilde{\alpha}|T$ is a CPNE of this game. Hence *T* has an internally consistent improvement upon $\tilde{\beta}$. As $T \neq N$ this is impossible because $\tilde{\beta}$ is self-enforcing. Thus, the desired contradiction has been obtained. Q.E.D.

5 An example

We shall show by means of an example that GMVS's may not be strongly coalition-proof. Let $\ell = 3$, $B^j = \{0, 1\}$ for j = 1, 2, 3, and $N = \{1, 2, 3\}$. We define

a GMVS f by means of the following left-coalition systems: $W^j : B^j \to 2^N$ is defined by $W^{j}(0) = \{S \subset N \mid S \text{ has at least two members}\}$ and $W^{j}(1) = 2^{N}$, for j = 1, 2, 3. Let $B = \times_{i=1}^{3} B^{j}$ and let e^{j} be the *j*-th unit vector in \mathbb{R}^{3} , j = 1, 2, 3. We define three additive $(u: B \to R \text{ is additive if } u(x + y) = u(x) + u(y)$ for all $x, y \in B$) utility functions on B as follows: $u_1(0) = 0$, $u_1(e^1) = 4$, $u_1(e^2) = -1$, and $u_1(e^3) = -2$; $u_2(0) = 0$, $u_2(e^1) = -1$, $u_2(e^2) = 4$, and $u_2(e^3) = -2$; $u_3(0) = 0$, $u_3(e^1) = -1$, $u_3(e^2) = -2$, and $u_3(e^3) = 4$. Let P_i be the preference relation represented by u_i , i = 1, 2, 3. Then P_i is single-peaked with bliss point e^i , i = 1, 2, 3. Now $f(e^1, e^2, e^2) = (0, 0, 0)$ because of our definition of $W^{j}(0)$, j = 1, 2, 3. However, (0, 0, 0) is not Pareto optimal. Indeed, let \hat{u}_1 be defined by $\hat{u}_1(0) = 0$, $\hat{u}_1(e^1) = 1$, $\hat{u}_1(e^2) = 2$, $\hat{u}_1(e^3) = 4$, and let $\hat{u}_2 = \hat{u}_3 = \hat{u}_1$ also be three additive utility functions on B. Denote by \hat{P}_i the preference relation represented by \hat{u}_i , i = 1, 2, 3. Clearly, $\tau(\hat{P}_i) = (1, 1, 1) = e$, i = 1, 2, 3, and f(e, e, e) = e. Also, $f(e, e, e)P_i f(e^1, e^2, e^3)$, i = 1, 2, 3. Moreover, because of our definition of $W^{j}(0), j = 1, 2, 3, (e, e, e)$ is an NE of the game $(B^{N}; f; P_{1}, P_{2}, P_{3})$. Hence, the truthtelling strategy (e^1, e^2, e^3) is not a strong CPNE.

6 Concluding remarks

In this paper we proved that the strongest kind of group stability satisfied by all multi-dimensional GMVS's is coalition-proofness. This result is very far from being a consequence of strategy-proofness. Indeed, Peleg (1998) shows that pivotal mechanisms are not coalition-proof. Also, our result does not follow from Dasgupta et al. (1979), because multi-dimensional GMVS's may not be group strategy-proof. We recall that Dasgupta et al. (1979) contains a detailed investigation of the relationship between strategy-proofness and group strategy-proofness. When the dimension is greater than one, our restricted domain of preferences is too small to yield the Dasgupta-Hammond-Maskin type of results.

References

Arrow, K.J. (1951) Social Choice and Individual values, Wiley, New York

Barberá, S., Gul, F., Stacchetti, E. (1993) Generalized median voter schemes and committees. Journal of Economic Theory 61: 262–289

Barberá, S., Sonnenschein, H., Zhou, L. (1991) Voting by committees. Econometrica 59: 595-609

- Bernheim, B.D., Peleg, B., Whinston, M.D. (1987) Coalition-proof Nash equilibria. I. Concepts. Journal of Economic Theory 42: 1–12
- Black, D. (1948) On the rationale of group decision making. Journal of Political Economy 56: 23-34
- Border, K., Jordan, J. (1983) Straightforward elections, unanimity, and phantom voters. *Review of economic Studies* 50: 153–170
- Dasgupta, P., Hammond, P., Maskin, E. (1979) The implementation of social choice rules: some general results on incentive compatibility. *The Review of Economic Studies* 46: 185–216
- Kaplan, G. (1992) Sophisticated outcomes and coalitional stability. M.Sc. Thesis, Department of Statistics, Tel-Aviv University (in English)

Moulin, H. (1980) On strategy-proofness and single-peakedness. Public Choice 35: 437-455

Peleg, B. (1998) Almost all equilibria in dominant strategies are coalition-proof. *Economic Letters* 60: 157–162